

A Strongly Effective Domain Model for the Calculus of Constructions

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Calculus of Constructions

(Coquand/Huet; *here*: notation by Hyland/Pitts)

Well-formed expressions are divided in 3 levels:

Terms, Orders, Operators

Metavariables:

Orders: K, L, M, \dots

Operators: S, T, U, \dots

Terms: s, t, u, \dots

Order constant: Type

(Types = Operators of Order “Type”)

Metavariables: A, B, C, \dots

The rules of the calculus allow the derivation of *Judgements*.

Structural Judgements:

$$\Gamma \vdash K : \text{Order}, \quad \Gamma \vdash S : K, \quad \Gamma \vdash S : A$$

Equality Judgements:

$$\Gamma \vdash K = L : \text{Order}, \quad \Gamma \vdash S = T : K, \quad \Gamma \vdash s = t : A$$

All judgements are made with respect to a *Context* Γ (Declaration of variables)

Contexts are built according to the following rules:

▶ $()$ context

▶
$$\frac{\Gamma \text{ context}}{\Gamma, X : \text{Order context}} \quad (X \notin \text{dom}(\Gamma))$$

▶
$$\frac{\Gamma \vdash K : \text{Order}}{\Gamma, Y : K \text{ context}} \quad (Y \notin \text{dom}(\Gamma))$$

▶
$$\frac{\Gamma \vdash S : \text{Type}}{\Gamma, x : S \text{ context}} \quad (x \notin \text{dom}(\Gamma))$$

Judgements can be derived by *general* rules:

- ▶ equality rules
- ▶ substitution
- ▶ assumption
- ▶ weakening

and *specific* rules

- ▶ Type $\frac{}{() \vdash \text{Type} : \text{Order}}$

Orders and Types are closed under “quantification” over both Orders and Types.

► Product clauses (“Types over Types”)

Formation
$$\frac{\Gamma, x : A \vdash C : \text{Type}}{\Gamma \vdash \Pi x : A. C : \text{Type}}$$

Introduction
$$\frac{\Gamma, x : A \vdash s : C}{\Gamma \vdash \lambda x : A. s : \Pi x : A. C}$$
 (abstraction)

Elimination
$$\frac{\Gamma \vdash t : \Pi x : A. C \quad \Gamma \vdash u : A}{\Gamma \vdash tu : C[u/x]}$$
 (application)

Equality
$$\frac{\Gamma \vdash u : A \quad \Gamma, x : A \vdash s : C}{\Gamma \vdash (\lambda x : A. s)u = s[u/x] : C[u/x]}$$

$$\frac{\Gamma \vdash t : \Pi x : A. C}{\Gamma \vdash \lambda x : A. tx = t : \Pi x : A. C}$$

► Sum clauses (“Types over Types”)

Formation
$$\frac{\Gamma, x : A \vdash C : \text{Type}}{\Gamma \vdash \Sigma x : A. C : \text{Type}}$$

Introduction
$$\frac{\Gamma \vdash s : A \quad \Gamma \vdash t : C[s/x]}{\Gamma \vdash \langle s, t \rangle : \Sigma x : A. C}$$

Elimination
$$\frac{\Gamma \vdash s : \Sigma x : A. C \quad \Gamma, x : A, y : C \vdash t : B[\langle x, y \rangle / z]}{\Gamma \vdash E(s, (x, y).t) : B[s/z]}$$

Equality
$$\frac{\Gamma \vdash s : A \quad \Gamma \vdash u : C[s/x] \quad \Gamma, x : A, y : C \vdash t : B[\langle x, y \rangle / z]}{\Gamma \vdash E(\langle s, u \rangle, (x, y).t) = t[s/x, u/y] : B[\langle s, u \rangle / z]}$$

$$\frac{\Gamma \vdash s : \Sigma x : A. C \quad \Gamma, z : \Sigma x : A. C \vdash t : B}{\Gamma \vdash E(s, (x, y).t[\langle x, y \rangle / z]) = t[s/z] : B[s/z]}$$

CC has λ^2 as a subsystem.

Coquand, Gunter and Winskel (model of λ^2):

Types $\xRightarrow{[\cdot]}$ dl-domains

here:

Types $\xRightarrow{[\cdot]}$ canonical representations
of dl-domains

|| Winskel

stable event structures

Terms $\xRightarrow{[\cdot]}$ elements of the
corresponding dl-domain

Advantage: *There is a natural substructure relation such that stable event structures form a domain that is similar to a dl-domain.*

Definition

Let (D, \sqsubseteq, \perp) be a Scott domain with set of compact elements D^0 .

1. D is a dl-domain if the following Axioms d and l are satisfied:

Axiom d: $(\forall x, y, z)[\{x, y, z\}^\uparrow \text{ (bounded)} \Rightarrow$

$$x \sqcap (y \sqcup z) = (x \sqcap y) \sqcup (x \sqcap z).$$

Axiom l: Each compact element dominates only finitely many elements.

2. An element $p \in D^0$ is *completely prime* if for all bounded $X \subseteq D$,

$$p \sqsubseteq \bigsqcup X \Rightarrow (\exists x \in X)p \sqsubseteq x.$$

Definition

Let D_1, D_2 be Scott domains. A map $f: D_1 \rightarrow D_2$ is said to be

1. *continuous*, if it is monotone and preserves least upper bounds of directed subsets.
2. *stable*, if it is continuous and preserves greatest lower bounds of bounded pairs of elements, i.e. for all $x, y \in D_1$,

$$x \uparrow y \Rightarrow f(x \sqcap y) = f(x) \sqcap f(y).$$

Note that for stable maps $f: D_1 \rightarrow D_2$ we have that for all $x' \in D_2^0$ there is a least $x \in D_1^0$ such that $x' \sqsubseteq f(x)$.

Definition

$$\text{trace}(f) = \{ (x, x') \in D_1^0 \times D_2^0 \mid x \text{ least with } x' \sqsubseteq f(x) \}.$$

Posets are categories with an arrow ι_x^y from x to y , exactly if $x \sqsubseteq y$. Greatest lower bounds of bounded pairs correspond to pullbacks in this case.

$$\begin{array}{ccc}
 x \sqcap y & \text{---} & y \\
 | & & | \\
 x & \text{---} & z
 \end{array}$$

$$\begin{array}{ccccc}
 X \times_Z Y & \xrightarrow{f} & X & & \\
 \downarrow g & & & & \downarrow h \\
 Y & \xrightarrow{k} & Z & &
 \end{array}$$

Definition

Let $\mathbf{C}_1, \mathbf{C}_2$ be categories with pullbacks. A functor $F: \mathbf{C}_1 \rightarrow \mathbf{C}_2$ is *stable*, if it preserves directed limits and pullbacks.

Definition

Let D_1, D_2 be Scott domains. A pair (e, p) of stable maps $e: D_1 \rightarrow D_2$ and $p: D_2 \rightarrow D_1$ is a *stable embedding/projection* if

- ▶ $p \circ e = \text{id}_{D_1}$
- ▶ $e \circ p \sqsubseteq \text{id}_{D_2}$.

Note that each component of such a pair uniquely determines the other one.

Let \mathbf{SD}^e be the category of all Scott domains with stable embeddings, D be a Scott domain and $F: D \rightarrow \mathbf{SD}^e$ be a stable functor.

For $x, y \in D$ with $x \sqsubseteq y$ we write $F_{x,y}$ for the embedding $F(\iota_x^y): F(x) \rightarrow F(y)$ and F_{xy}^R for the corresponding projection.

Definition

A family $f = (f_d)_{d \in D}$ with $f_d \in F(d)$ is said to be

1. *monotone* if

$$x \sqsubseteq y \Rightarrow F_{xy}(f_x) \sqsubseteq f_y.$$

2. *continuous* if it is monotone and for all directed $S \subseteq D$,

$$f_{\bigsqcup S} = \bigsqcup \{ F_{x, \bigsqcup S}(f_x) \mid x \in S \}.$$

3. *stable* if it is continuous and for all $x, y \in D$ with $x \uparrow y$

$$F_{x \sqcap y, x}^R(f_x) \sqcap F_{x \sqcap y, y}^R(f_y) = f_{x \sqcap y}.$$

As in the case of stable maps, for each $x' \in \bigcup \{ F(x)^0 \mid x \in D \}$ there is a least $x_0 \in D^0$ such that $x' \in F(x_0)^0$ and $x' \sqsubseteq f_{x_0}$. Let

$$\text{trace}(f) = \{ (x, x') \in (\sum_{x \in D} F(x))^0 \mid x \text{ least with } x' \sqsubseteq f_x \}.$$

Definition

1. An *event structure* $E = (E, \text{Con}, \vdash)$ is given by
 - ▶ a set E of *events*,
 - ▶ a nonempty predicate $\text{Con} \subseteq \mathcal{P}_{fin}(E)$, called *consistency*, such that

$$X \in \text{Con} \wedge Y \subseteq X \Rightarrow Y \in \text{Con},$$

- ▶ a relation $\vdash \subseteq \text{Con} \times E$, called *enabling relation*.
2. An event structure E is *stable* if for $e \in E$ and $X, Y \subseteq E$

$$X \vdash e \wedge Y \vdash e \wedge X \cup Y \cup \{e\} \in \text{Con} \Rightarrow X = Y.$$

Every stable event structure gives rise to a dl-domain and vice versa.

Definition

1. A *proof* τ of an event e is a set of events defined recursively by
 - ▶ $\emptyset \vdash e \Rightarrow \tau = \emptyset$.
 - ▶ If τ_1, \dots, τ_n are proofs of e_1, \dots, e_n and $\{e_1, \dots, e_n\} \vdash e$, then $\tau_1 \cup \{e_1\} \cup \dots \cup \tau_n \cup \{e_n\}$ is a proof of e .
2. A *state* x is a subset of E which is
 - ▶ *finitely consistent*, i.e., $(\forall X \subseteq_f x) X \in \text{Con}$.
 - ▶ *safe*, i.e., x contains proof of e , for all $e \in x$.

Proposition

1. Let $\mathcal{S}^+(E)$ be the set of all states of E . Then $(\mathcal{S}^+(E), \subseteq)$ is a *dl-domain*.
2. Let D be a *dl-domain* and $\mathcal{S}^-(D)$ be the set of its complete primes. Moreover, for $X \subseteq_f \mathcal{S}^-(D)$ and $p \in \mathcal{S}^-(D)$ let
 - ▶ $X \in \text{Con}$ if X is bounded
 - ▶ $X \vdash p$ if X is the set of complete primes immediately below p .

Then $(\mathcal{S}^-(D), \text{Con}, \vdash)$ is a *stable event structure* with

$$D \cong \mathcal{S}^+(\mathcal{S}^-(D)).$$

Set

$$\mathcal{W} = \{ E \subseteq \omega \mid E \text{ is stable event structure} \}.$$

Definition

Let $A, B \in \mathcal{W}$. $A \trianglelefteq B$ if

▶ $A \subseteq B$

▶ $\text{Con}_A = \text{Con}_B \cap \mathcal{P}_{fin}(A)$

(No new consistent subsets of A w.r.t. Con_B)

▶ $\vdash_A \subseteq \vdash_B$

▶ $(\forall e \in A)(\forall X \in \text{Con}_B) X \vdash_B e \Rightarrow X \subseteq A \wedge X \vdash_A e$

(\vdash_B allows no additional enablings w.r.t. A).

Proposition

$(\mathcal{W}, \sqsubseteq)$ is a locally distributive stable ω -bifinite domain, i.e.,

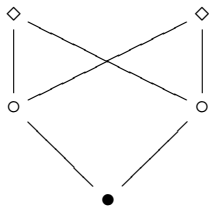
- ▶ ω -algebraic
- ▶ $\{x, y\} \uparrow \Rightarrow x \sqcap y$ exists
- ▶ every principal ideal is distributive
- ▶ $x \uparrow \bigsqcup X \Rightarrow x \sqcap \bigsqcup X = \bigsqcup \{x \sqcap z \mid z \in X\}$, for all $x \in \mathcal{W}$ and all directed subsets X of \mathcal{W}
- ▶ $(U \downarrow)^\infty(X)$ is finite, for all finite sets X of compact elements of \mathcal{W} .

$$(U \downarrow)^\infty(X) = \bigcup_{n \in \omega} (U \downarrow)^n(X)$$

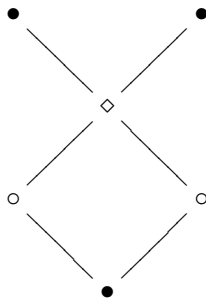
$$(U \downarrow)(X) = \bigcup \{ \text{MUB}(Y) \mid Y \subseteq_f \downarrow X \}.$$

Thus \mathcal{W} is nearly a dl-domain:

Here, a finite bounded set can have *finitely many* minimal upper bounds, whereas in a dl-domain it has *exactly one* minimal upper bound.



now
finitely many minimal upper
bounds



dl
exactly one minimal upper bound

Since ω -bifinite domains are algebraic, they are completely determined by their compact elements

Proposition

Let D be an algebraic domain and D^0 be the subset of its compact elements. Set

$$\mathcal{R}^-(D) = (D^0, \sqsubseteq \upharpoonright D^0)$$

$$\mathcal{R}^+(D) = (\text{ideal completion of } D^0, \sqsubseteq).$$

Then

$$D \cong \mathcal{R}^+(\mathcal{R}^-(D)).$$

$\mathcal{B} = \{ A \subseteq \omega \mid A \text{ algebraic base of a stable locally distributive } \omega\text{-bifinite domain} \}$

Definition

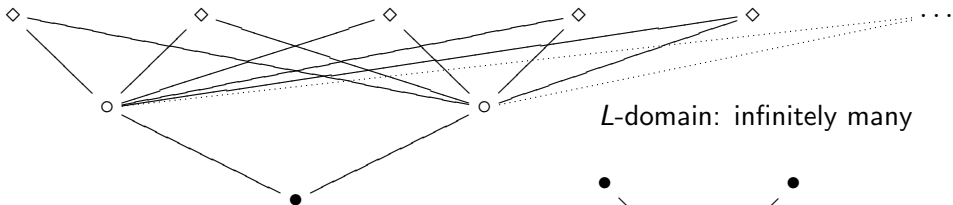
Let $A, C \in \mathcal{B}$. $A \Subset C$ if

- ▶ $A \subseteq C$
- ▶ $(\forall a, b \in A) a \sqsubseteq_A b \Leftrightarrow a \sqsubseteq_C b$
- ▶ $(\forall a \in A)(\forall b \in C) b \sqsubseteq_C a \Rightarrow b \in A$
- ▶ $(\forall X \subseteq_f A) \text{MUB}_C(X) \subseteq A$

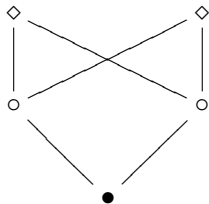
Proposition

(\mathcal{B}, \Subset) is a locally distributive ω -algebraic L-domain that satisfies Berry's finiteness condition, i.e., $\downarrow\{A\}$ is finite, for all $A \in \mathcal{B}^0$.

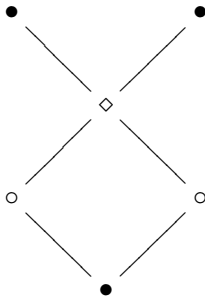
Hence \mathcal{B} is nearly a dl-domain.



L-domain: infinitely many



ω -bifinite: finitely many



dl: exactly one

minimal upper bound(s)

Intended Interpretation

- ▶ Type expression α with free variables in Γ by a stable map

$$\llbracket \alpha \rrbracket_{\Gamma} : \llbracket \Gamma \rrbracket \rightarrow \mathcal{W}$$

- ▶ Term expression t of Type α with free variables in Γ by a stable family

$$\left(\llbracket t \rrbracket_{\Gamma}(x) \right)_{x \in \llbracket \Gamma \rrbracket} \text{ with } \llbracket t \rrbracket_{\Gamma}(x) \in \mathcal{S}^+(\llbracket \alpha \rrbracket_{\Gamma}(x))$$

- ▶ Order expression σ with free variables in Γ by a stable map

$$\llbracket \sigma \rrbracket_{\Gamma} : \llbracket \Gamma \rrbracket \rightarrow \mathcal{B}$$

- ▶ Operator expression T of Order σ with free variables in Γ by a stable family

$$\left(\llbracket T \rrbracket_{\Gamma}(x) \right)_{x \in \llbracket \Gamma \rrbracket} \text{ with } \llbracket T \rrbracket_{\Gamma}(x) \in \mathcal{R}^+(\llbracket \sigma \rrbracket_{\Gamma}(x))$$

Let

$\omega\mathbf{dLI}$ category of locally distributive
 ω -algebraic L -domains with
Berry's axiom I

$\omega\mathbf{Bif}_\wedge$ category of locally distributive
stable ω -bifinite domains

\mathbf{DI} category of dl-domains

always with stable maps as morphisms

Proposition

Let $D \in \omega\mathbf{dLI}$.

1. $F : D \rightarrow \mathcal{W}$ stable $\Rightarrow \mathcal{S}^+ \circ F : D \rightarrow \mathbf{DI}$ stable functor
2. $F : D \rightarrow \mathcal{B}$ stable $\Rightarrow \mathcal{R}^+ \circ F : D \rightarrow \omega\mathbf{Bif}_\wedge$ stable functor

$$\llbracket \Gamma \rrbracket = ?$$

- ▶ $\llbracket () \rrbracket = \text{one-point domain}$
- ▶ $\llbracket \Gamma, X : \text{Order} \rrbracket = \llbracket \Gamma \rrbracket \times \mathcal{B}$
- ▶ $\llbracket \Gamma, X : K \rrbracket = ?$
- ▶ $\llbracket \Gamma, x : A \rrbracket = ?$

Suppose

$\Gamma \vdash K : \text{Order}$.

Then

$$\mathcal{R}^+ \circ \llbracket K \rrbracket_{\Gamma} : \llbracket \Gamma \rrbracket \rightarrow \omega \mathbf{Bif}_{\wedge}$$

is a stable functor. Construct

$$\sum_{\llbracket \Gamma \rrbracket} \mathcal{R}^+ \circ \llbracket K \rrbracket_{\Gamma} = \{ (x, y) \mid x \in \llbracket \Gamma \rrbracket \wedge y \in \mathcal{R}^+(\llbracket K \rrbracket_{\Gamma}(x)) \}$$

$$(x, y) \sqsubseteq (x', y') \Leftrightarrow x \sqsubseteq_{\llbracket \Gamma \rrbracket} x' \wedge y \sqsubseteq_{\mathcal{R}^+(\llbracket K \rrbracket_{\Gamma}(x'))} y'$$

[Note: $\mathcal{R}^+(\llbracket K \rrbracket_{\Gamma}(x)) \subseteq \mathcal{R}^+(\llbracket K \rrbracket_{\Gamma}(x'))$]

► $\llbracket \Gamma, X : K \rrbracket = \sum_{\llbracket \Gamma \rrbracket} \mathcal{R}^+ \circ \llbracket K \rrbracket_{\Gamma}$

$$\frac{\Gamma, x : A \vdash C : \text{Type}}{\Gamma \vdash \Pi x : A. C : \text{Type}}$$

Suppose

- ▶ $\llbracket C \rrbracket_{\Gamma, x:A} : \sum_{\llbracket \Gamma \rrbracket} \mathcal{S}^+ \circ \llbracket A \rrbracket_{\Gamma} \rightarrow \mathcal{W}$ is stable
- ▶ $\llbracket A \rrbracket_{\Gamma} : \llbracket \Gamma \rrbracket \rightarrow \mathcal{W}$ is stable.

Let $z \in \llbracket \Gamma \rrbracket$ be fixed. Then

- ▶ $\llbracket A \rrbracket_{\Gamma}(z) \in \mathcal{W}$
- ▶ $\lambda d. \llbracket C \rrbracket_{\Gamma, x:A}(z, d) : \mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z)) \rightarrow \mathcal{W}$ stable.

Set

$$\prod_{\mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))} \lambda d. \mathcal{S}^+ \circ \llbracket C \rrbracket_{\Gamma, x:A}(z, d) =$$
$$\{ (f_d)_{d \in \mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))} \mid (f_d) \text{ stable family: } f_d \in \mathcal{S}^+(\llbracket C \rrbracket_{\Gamma, x:A}(z, d)) \}$$

$$f \sqsubseteq g \Leftrightarrow \text{trace}(f) \subseteq \text{trace}(g)$$

Lemma

$$\left(\prod_{\mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))} \lambda d. \mathcal{S}^+ \circ \llbracket C \rrbracket_{\Gamma, x:A}(z, d), \sqsubseteq \right) \in \mathbf{DI}.$$

Thus, there is a stable event structure

$$\Pi_{\llbracket A \rrbracket_{\Gamma}(z)} \llbracket C \rrbracket_{\Gamma, x:A}^z \quad (1)$$

in \mathcal{W} such that

$$\mathcal{S}^+(\Pi_{\llbracket A \rrbracket_{\Gamma}(z)} \llbracket C \rrbracket_{\Gamma, x:A}^z) \xleftrightarrow{F_z} \prod_{\mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))} \lambda d. \mathcal{S}^+ \circ \llbracket C \rrbracket_{\Gamma, x:A}(z, d).$$

Note that (1) can be constructed from $\llbracket A \rrbracket_{\Gamma}$ and $\llbracket C \rrbracket_{\Gamma, x:A}$ such that

$$\Pi(\llbracket A \rrbracket_{\Gamma}, \llbracket C \rrbracket_{\Gamma, x:A}) : z \in \llbracket \Gamma \rrbracket \mapsto \Pi_{\llbracket A \rrbracket_{\Gamma}(z)} \llbracket C \rrbracket_{\Gamma, x:A}^z$$

is stable. Define

$$\blacktriangleright \llbracket \Pi x : A. C \rrbracket_{\Gamma} = \Pi(\llbracket A \rrbracket_{\Gamma}, \llbracket C \rrbracket_{\Gamma, x:A})$$

$$\frac{\Gamma, x : A \vdash s : C}{\Gamma \vdash \lambda x : A. s : \prod x : A. C}$$

Suppose

- ▶ $\llbracket A \rrbracket_{\Gamma} : \llbracket \Gamma \rrbracket \rightarrow \mathcal{W}$ is stable
- ▶ $\llbracket C \rrbracket_{\Gamma, x:A} : \sum_{\llbracket \Gamma \rrbracket} \mathcal{S}^+ \circ \llbracket A \rrbracket_{\Gamma} \rightarrow \mathcal{W}$ is stable
- ▶ $(\llbracket s \rrbracket_{\Gamma}(z, d))_{(z,d) \in \sum_{\llbracket \Gamma \rrbracket} \mathcal{S}^+ \circ \llbracket A \rrbracket_{\Gamma}}$ is a stable family such that

$$\llbracket s \rrbracket_{\Gamma}(z, d) \in \mathcal{S}^+(\llbracket C \rrbracket_{\Gamma, x:A}(z, d)).$$

Fix $z \in \llbracket \Gamma \rrbracket$. Then

$$(\llbracket s \rrbracket_{\Gamma}^z(d))_{d \in \mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))} = (\llbracket s \rrbracket_{\Gamma}(z, d))_{d \in \mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))}$$

is a stable family such that

$$\begin{array}{c} (\llbracket s \rrbracket_{\Gamma}^z(d))_{d \in \dots} \in \prod_{\mathcal{S}^+(\llbracket A \rrbracket_{\Gamma}(z))} \lambda d. \mathcal{S}^+(\llbracket C \rrbracket_{\Gamma, x:A}(z, d)) \\ \downarrow F_z^{-1} \\ \mathcal{S}^+(\prod_{\llbracket A \rrbracket_{\Gamma}(z)} \llbracket C \rrbracket_{\Gamma, x:A}^z) \\ \parallel \\ \mathcal{S}^+(\llbracket \prod x : A. C \rrbracket_{\Gamma}(z)) \end{array}$$

Note that

$$\text{curry}(\llbracket s \rrbracket_{\Gamma}) : z \in \llbracket \Gamma \rrbracket \mapsto F_z^{-1}((\llbracket s \rrbracket_{\Gamma}^z(d))_{d \in \dots})$$

is stable. Define

► $\llbracket \lambda x : A. s \rrbracket_{\Gamma} = \text{curry}(\llbracket s \rrbracket_{\Gamma})$

Advantages of this model:

- ▶ Conceptually much easier than other models which make heavy use of category theory.
- ▶ Recursion can be dealt with without any extra effort.
- ▶ Disjoint unions and definitions by cases can easily be added.
- ▶ Effectively given: all operations are computable in a strong sense: their traces are effectively enumerable.