Einstein-Podolsky-Rosen correlations and Bell correlations in the simplest scenario

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Introduction

- Steering is a nonclassical phenomenon that formalizes what Einstein called "spooky action at a distance". For a long time, it was studied under the name of Einstein-Podolsky-Rosen (EPR) paradox.
- It is a form of nonlocality that sits between entanglement and Bell nonlocality and that is intrinsically asymmetric.
- It can be characterized by a simple quantum information processing task, namely, entanglement verification with an untrusted party.
- It is useful in a number of applications, such as subchannel discrimination and one-sided device-independent quantum key distribution.

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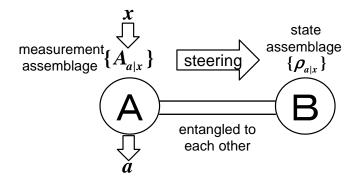


Figure: Steering scenario. Alice can affect Bob's state via her choice of the measurement according to the relation $\rho_{a|x} = \text{tr}_A[(A_{a|x} \otimes 1)\rho]$. Entanglement is necessary but not sufficient for steering.

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LHV model vs. LHV-LHS model

• Local hidden variable (LHV) model

$$p(a,b|x,y) = \sum_{\lambda} p_{\lambda} p(a|x,\lambda) p(b|y,\lambda).$$

 $p(a|x,\lambda), p(b|y,\lambda)$: arbitrary probability distributions,

• Local hidden variable-local hidden state (LHV-LHS) model¹,

$$p(a,b|x,y) = \sum_{\lambda} p_{\lambda} p(a|x,\lambda) p(b|y,\rho_{\lambda}).$$

 $p(a|x, \lambda)$: arbitrary probability distributions, $p(b|y, \rho_{\lambda}) = tr(\rho_{\lambda}B_{b})$: probability distributions from Born rule.

The set of probability distributions p(a, b|x, y) is EPR nonlocal (Bell) if it does not admit any LHV-LHS (LHV) model.

¹Werner, PRA, 40, 4277 (1989); Wiseman et al., PRL **98**, 140402 (2007). ≥ Huangjun Zhu (Cologne University) Simplest steering scenario August 31, 2017 4/19

Simplest Bell scenario and Simplest Steering scenario

Simplest Bell scenario: Two dichotomic measurements for Alice and Bob, respectively.

The set of correlations is Bell nonlocal iff it violates the CHSH inequality.

Simplest steering scenario:

- 1. Two dichotomic measurements for Alice and Bob, respectively.
- 2. Two dichotomic measurements for Alice and one trine measurement for Bob.

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Which two-qubit states can generate EPR-nonlocal correlations in the simplest scenario?

What are the connections with the simplest Bell scenario?

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Measurement and state assemblages

- A positive-operator-valued measure (POVMs) is composed of a set of positive operators that sum up to the identity.
- A measurement assemblage $\{A_{a|x}\}$ is a collection of POVMs.
- Ensembles and state assemblages:

$$\rho_{a|x} = \operatorname{tr}[(A_{a|x} \otimes 1)\rho], \quad \sum_{a} \rho_{a|x} = \rho_{B} = \operatorname{tr}_{A}(\rho). \tag{1}$$

The set of unnormalized states $\rho_{a|x}$ for a given measurement *x* is an ensemble for ρ_B , and the whole collection $\{\rho_{a|x}\}$ a state assemblage

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Steering and local hidden state model

• The assemblage $\{\rho_{a|x}\}$ admits a local hidden state model if

$$\rho_{\boldsymbol{a}|\boldsymbol{x}} = \sum_{\lambda} \boldsymbol{p}(\boldsymbol{a}|\boldsymbol{x},\lambda) \sigma_{\lambda} \quad \forall \boldsymbol{a}, \boldsymbol{x},$$
(2)

where $\{\sigma_{\lambda}\}$ is an ensemble for ρ_B and $p(a|x, \lambda)$ are a collection of stochastic maps.

- The assemblage {\(\rho_{a|x}\)\)} is steerable it does not admit a local hidden state model.
- The state ρ is steerable from Alice to Bob if there exists a measurement assemblage for Alice such that the resulting state assemblage for Bob is steerable.

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Restricted LHS model

Let V ≤ B(H) be a subspace of the operator space. The assemblage {ρ_{a|x}}_{a,x} admits a V-restricted LHS model if

$$\operatorname{tr}(\Pi\rho_{\boldsymbol{a}|\boldsymbol{x}}) = \sum_{\lambda} \boldsymbol{p}_{\lambda} \boldsymbol{p}(\boldsymbol{a}|\boldsymbol{x},\lambda) \operatorname{tr}(\Pi\rho_{\lambda}) \quad \forall \ \Pi \in \mathcal{V}.$$

Otherwise, it is \mathcal{V} -steerable.

• Let \mathcal{R} be the space spanned by all the effects B_b .

 $\{p(a, b|x, y)\}$ is EPR nonlocal $\iff \{\rho_{a|x}\}_{a,x}$ is \mathcal{R} -steerable.

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Consider the two-qubit state

$$\rho = \frac{1}{4} \left(I \otimes I + \alpha \cdot \sigma \otimes I + I \otimes \beta \cdot \sigma + \sum_{i,j=1}^{3} t_{ij} \sigma_i \otimes \sigma_j \right),$$

Alice and Bob can choose two projective measurements as described by $\{A_1, A_2\} = \{a_1 \cdot \sigma, a_2 \cdot \sigma\}$ and $\{B_1, B_2\} = \{b_1 \cdot \sigma, b_2 \cdot \sigma\}$.

Assemble of Bob induced by Alice,

$$\rho_{\pm|m} = \frac{1}{4} \left[(1 \pm \alpha \cdot \boldsymbol{a}_m) \boldsymbol{l} + \boldsymbol{\beta} \cdot \boldsymbol{\sigma} \pm \gamma_m \cdot \boldsymbol{\sigma} \right]$$

where $\gamma_{mj} = \sum_{i=1}^{3} a_{mi} t_{ij}$.

• Assemblage after projection:

$$\tilde{\rho}_{\pm|m} = \frac{1}{4} [(1 \pm \alpha \cdot \boldsymbol{a}_m) \boldsymbol{l} + \tilde{\beta} \cdot \boldsymbol{\sigma} \pm \tilde{\gamma}_m \cdot \boldsymbol{\sigma}],$$

where $\tilde{\beta}$ and $\tilde{\gamma}_m$ are the projection of and β and γ_m on the plane spanned by b_1, b_2 .

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Assemble of Bob induced by Alice,

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where $\gamma_{mj} = \sum_{i=1}^{3} a_{mi} t_{ij}$.

• Assemblage after projection:

$$\tilde{\rho}_{\pm|m} = \frac{1}{4} \big[(1 \pm \alpha \cdot \boldsymbol{a}_m) \boldsymbol{l} + \tilde{\boldsymbol{\beta}} \cdot \boldsymbol{\sigma} \pm \tilde{\boldsymbol{\gamma}}_m \cdot \boldsymbol{\sigma} \big],$$

where $\tilde{\beta}$ and $\tilde{\gamma}_m$ are the projection of and β and γ_m on the plane spanned by $\boldsymbol{b}_1, \boldsymbol{b}_2$.

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Necessary and sufficient steering criterion

- The state ρ is steerable under the measurement setting {a₁ · σ, a₂ · σ} and {b₁ · σ, b₂ · σ} iff the assemblage {ρ_{±|m}} is steerable.
- Equivalently, the two effects $O_{+|1}$ and $O_{+|2}$ are not coexistent, where

$$O_{\pm|m} = \tilde{\rho}_{\mathrm{B}}^{-1/2} \tilde{\rho}_{\pm|m} \tilde{\rho}_{\mathrm{B}}^{-1/2} = O_{\pm|m} = \frac{1}{2} [(1 \pm \eta_m) I \pm \mathbf{r}_m \cdot \boldsymbol{\sigma}]$$

are known as steering-equivalent observables.

O_{+|1} and O_{+|2} are coexistent iff²

$$(1 - F_1^2 - F_2^2) \Big(1 - \frac{\eta_1^2}{F_1^2} - \frac{\eta_2^2}{F_2^2} \Big) \le (\mathbf{r}_1 \cdot \mathbf{r}_2 - \eta_1 \eta_2)^2,$$

where

$$F_m = \frac{1}{2} \Big(\sqrt{(1 + \eta_m)^2 - r_m^2} + \sqrt{(1 - \eta_m)^2 - r_m^2} \Big).$$

²S. Yu, N.-I. Liu, L. Li, and C. H. Oh, PRA 81, 062116 (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) - (2010) -

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Theorem

In the simplest steering scenario, the set of full correlations is EPR nonlocal iff the analog CHSH inequality

$$egin{aligned} &|\langle (\pmb{A}_1+\pmb{A}_2)\pmb{B}_1
angle \pmb{b}_1'+\langle (\pmb{A}_1+\pmb{A}_2)\pmb{B}_2
angle \pmb{b}_2'|\ &+|\langle (\pmb{A}_1-\pmb{A}_2)\pmb{B}_1
angle \pmb{b}_1'+\langle (\pmb{A}_1-\pmb{A}_2)\pmb{B}_2
angle \pmb{b}_2'|\leq 2 \end{aligned}$$

is violated, where $\mathbf{b}_1', \mathbf{b}_2'$ form the dual basis of $\mathbf{b}_1, \mathbf{b}_2$.

When Bob's measurements are mutually unbiased, the criterion reduces to that derived by Cavalcanti et al.

$$\frac{\sqrt{\langle (A_1 + A_2)B_1 \rangle^2 + \langle (A_1 + A_2)B_2 \rangle^2}}{+\sqrt{\langle (A_1 - A_2)B_1 \rangle^2 + \langle (A_1 - A_2)B_2 \rangle^2}} \le 2$$

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Theorem

The maximal violation S of the analog CHSH inequality by any two-qubit state with correlation matrix T is equal to the maximal violation of the CHSH inequality, namely, $S = 2\sqrt{\lambda_1 + \lambda_2}$, where λ_1, λ_2 are the two largest eigenvalues of TT^T . Both inequalities are violated iff $\lambda_1 + \lambda_2 > 1$.

Corollary

A two-qubit state can generate Bell-nonlocal correlations in the simplest nontrivial scenario iff it can generate EPR-nonlocal full correlations.

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Strict hierarchy between steering and Bell nonlocality Consider a convex combination of the singlet and a product state,

$$o = s(|\Psi_{-}\rangle\langle\Psi_{-}|) + (1-s)(|0\rangle\langle0|)\otimesrac{1}{2}.$$

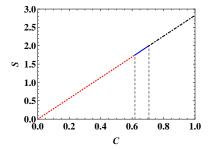


Figure: Black region: states that can generate Bell-nonlocal correlations or EPR-nonlocal full correlations in the simplest scenario. Blue region: states that are steerable in the same scenario, but cannot generate Bell-nonlocal correlations or EPR-nonlocal full correlations.

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Simplest and strongest one-way steering

Consider the two-qubit state³,

$$ho(oldsymbol{
ho}, heta)=oldsymbol{
ho}(|\psi(heta)
angle\langle\psi(heta)|)+(1-oldsymbol{
ho})\Big[rac{l}{2}\otimes
ho_{
m B}(heta)\Big],$$

where $|\psi(\theta)\rangle = \cos \theta |00\rangle + \sin \theta |11\rangle$.

- Violate the analog CHSH inequality iff $p^2 [1 + \sin^2(2\theta)] > 1$.
- Not unsteerable from Bob to Alice by arbitrary projective measurements if

$$\cos^2(2 heta) \geq rac{2p-1}{(2-p)p^3}.$$

• Alice can steer Bob in the simplest scenario iff $p > 1/\sqrt{2}$.

³J. Bowles, F. Hirsch, M. T. Quintino, and N. Brunner, PRA 93, 022121 (2016) 🤊 🔍

Simplest steering scenario

Simplest and strongest one-way steering

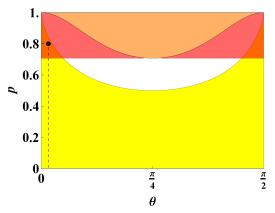


Figure: Orange: violate the (analog) CHSH inequality. Red: steerable from Alice to Bob in the simplest steering scenario, but cannot violate the (analog) CHSH inequality. Yellow: not steerable from Bob to Alice by arbitrary projective measurements. Intersection of the red region and the yellow region: demonstrate the simplest and strongest one-way steering.

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Simplest one-way steering with respect to POVMs

Consider the state

$$\rho = \frac{1}{4} \left[I \otimes I + p \cos(2\theta) \sigma_3 \otimes I + \cos^2 \theta I \otimes \sigma_3 + p \cos \theta (\sin \theta \sigma_1 \otimes \sigma_1 - \sin \theta \sigma_2 \otimes \sigma_2 + \cos \theta \sigma_3 \otimes \sigma_3) \right].$$

- No violation of the (analog) CHSH inequality
- Not unsteerable from Bob to Alice by arbitrary POVMs if

$$\cos^2(2 heta) \geq rac{2p-1}{(2-p)p^3}.$$

• Alice can steer Bob in the simplest scenario for some parameter range, say p = 0.825 and $\theta = 0.020$.

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Summary and an open question

- A two-qubit state can generate EPR-nonlocal full correlations in the simplest nontrivial scenario iff it can generate Bell-nonlocal correlations⁴.
- When full statistics is taken into account, the same scenario can demonstrate one-way steering and the hierarchy between steering and Bell nonlocality in the simplest and strongest form.

Does there exist a two-qubit state that is not steerable in the simplest scenario, but is steerable in the second simplest scenario in which Alice performs two dichotomic measurements and Bob performs full tomography?

⁴PRA 95, 062111 (2017)

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Thank You!

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